

# Mathematical Modeling of Cancer Cells and Chemotherapy Protocol Dealing Optimization Using Fuzzy Differential Equations And Lypunov Stability Criterion

Hadi Abbasnejad

Department of Electrical Engineering, Ahar Branch, Islamic Azad University, Ahar, Iran  
[abbasnejad.hadi@yahoo.com](mailto:abbasnejad.hadi@yahoo.com)

## Abstract

*Mathematical models can simulate the growth and proliferation of cells in the interaction with healthy cells, the immune system and measure the toxicity of drug and its effects on healthy tissue pay. One of the main goals of modeling the structure and growth of cancer cells is to find a control model suitable for administration among patients. In this study, a new mathematical model is designed to describe the changes in different phases of the cycle T cell proliferation, the population of immune cells, the proposed concentration of drug toxicity and treatment using differential equation and fuzzy Lyapunov stability, an optimal treatment protocol. One feature to consider is the rate of clearance of the drug in the body.*

**Keywords:** The optimal treatment protocol, Mathematical modeling of cancer, fuzzy differential equations, Lyapunov stability criteria

## 1- Introduction

Cancer is one of the most important factors of human morbidity and mortality; throughout the world there has always been the department of engineering science professionals' attention and basic science courses and extensive research and modeling in ways its treatment has taken place. Among the methods of cancer treatment, chemotherapy has been considered useful as a significant side effect, with serious damages to the healthy tissues of the patient. By optimizing the timing of injection, drug harms of this treatment can be reduced to a low level. For this purpose mathematical model system is necessary. Mathematical

models can simulate the growth and proliferation of cancer cells in contrast to healthy cells of the bodies' immune system and chemical agents used in the treatment of cancer and ensuring and measuring the toxicity of drug and its effects on healthy tissue pay. Mathematical models for cancer, depending on the model and level of detail provided, are intended to include a large variety of different types of differential equations. Obviously, a reliable protocol designed to be a more accurate Mathematical model was used to simulate system behavior [22, 23]. Mechanism of action of chemical agents used to treat cancer is that cells in a particular phase of proliferation (including phases  $G_1, S, G_2, U$ ) has held and to continue

advancing in the cycle stops, the immune cells to attack cancer cells and destroy them normally. For example, drugs (Ara-C) cytosine, Arabino side, 5- Fluorouracil, and prednisone are among them. In phases  $G_1, S$  and drugs vincristine, paclitaxel and Bleomycin act in  $M$  phases [1], [2]. Many mathematical models are offered, all of the cancer cells in a tumor population considered [3], [6]. But on closer look, since most drugs on cancer cells in a specific phase of the cycle affect cell proliferation, the middle population density of cancer cells in different phases of the cycle will provide treatment closer to the real system. Including recent research on the modeling of cells in different phases of the cell cycle, works of Webb [7], Kheifetz [8], Birkhead [9] and Swan [10] can be noted. Chemotherapy drugs' act in particular in their review article mentioned has been mentioned. Pannetta and Kirschner [11], the effects of the immune system as an adjunct in the chemotherapy are considered. Villasana [12], chemotherapy drugs act in a particular phase, as well as the effects of immune cells in the model, but the model did not consider the rest of cells. Kuzusko [13], based his idea on experimental data and mathematical models. To study the interaction between cancer cells and a drug operation, a particular phase has to be offered. A complete study in the field of mathematical modeling and control of cell proliferation cycle was carried out by Kimmel and Swierniak [4]. The conventional method for designing an optimal treatment protocol was introduced using the classical optimal control [14], [15].

In [3], a complete summary of recent efforts in the field of modeling control the growth of cancer cells is provided. In this paper, in the second part, a new mathematical model to describe the changes in different phases of the cell cycle T cell proliferation, the concentration and cytotoxicity of immune cells have been suggested. The third section is a short description on the balance system. In part four, with the introduction of a candidate Lyapunov function, asymptotic stability control law to ensure the overall results and in part five, with the control, protocol design for a hypothetical patient would return results.

## 2- Mathematical Modeling

The model in this study, changes in four cell populations, the concentration of the chemical drug used and provided. This model is similar to models [12], [16] which will provide the correct words to them, but they are fundamentally different. First, the models [12], [16] change healthy cells in the population not considered. The effect of drugs on the tissue due to the side effects of chemical drugs is essential. The changes in toxic chemical agents, as a parameter to see the effect of the drug on healthy tissue of the patient, single phase differential equation models will be added. The second difference is easy access if medication based on Lyapunov stability theorem using Fuzzy differential equation, dynamic effects rather than final in front of the Mass- action has been taken into consideration. The model presented in this study matched the growth

of healthy cells and cancer cells and the growth is assumed to be final. Population changes in cancer cells in different phases of cell cycle individually and through the cells of the middle phase is considered. Competition of immune cells and cancer cells in a model of prey- predator is assumed. Patients' blood plasma is mixed

$$\dot{x} = \alpha_3 z - \alpha_1 x - \delta_1 x - K_1 I_x \quad (1)$$

$$\dot{y} = \alpha_1 x(t - \tau) - \alpha_2 y - \delta_2 y - K_2 I_y - K_4 u y \quad (2)$$

$$\dot{z} = z \alpha_2 y - \alpha_3 z - \delta_3 z - K_3 I_z \quad (3)$$

$$\dot{I} = K + \frac{\rho I(x + y + z)^h}{\alpha + (x + y + z)^h} - \delta_4 I - (c_1 x + c_2 y - c_3 z) I - K_6 u I \quad (4)$$

$$\dot{u} = V - \gamma \eta \quad , \dot{s} = u - \eta s \quad (5)$$

In the above equation  $[x(t)]$  of cancer cells in the intermediate phase,  $[y(t)]$  of cancer cells in the mitosis phase,  $[z(t)]$  population as cancer cells in the stationary phase,  $[I(t)]$  the population of immune cells,  $[u(t)]$  the drug concentration and  $[s(t)]$  shows the effects of the drug. Basically, the Fuzzy differential equation with positive initial conditions are  $y(0)=y_0$   $z(0)=z_0$   $I(0)=I_0$  ,  $x(t)=\phi_1(t)(t \in [-\tau, 0])$ ,  $u(0)=u_0$  ,  $s(0)=s_0$  The equation is shown as  $\dot{x}$ , describing the changes population cancer cells present in the middle phase ( $G_1, s, G_2$ ), respectively. In the equation  $\alpha_3 z$  arrival rate of cells in stationary phase, middle phase shows. In this case, it is assumed that cells in the stationary phase accidentally have left this phase, the either start its activities in the cell cycle or are released into the bloods' stream (in other words, with a cell death). Phrases  $\alpha_1 x$  ,  $\delta_1 x$ , are in the rate of cancer

and their effects on tissue caused cancer. The effect of chemical drugs – induced toxicity on immune cells is observed. Accordingly, the model for Fuzzy differential equations a bunch (DDE-delayed) the following shall be provided in accordance with the:

cells from the middle phase to phase of mitosis cancer cells by the immune cells as a competitive show words  $k_1 I_x$  , the death rate of cancer cells by the immune cells as a competitive show. The equation  $\dot{y}$  describes changes of cancer cells in the mitotic phase. In this equation  $\alpha_1 x(t - \tau)$  shows arrival rates of cancer cells from the middle phase to mitosis phase. Now, at the beginning of mitosis phase of the cell it assumes  $\tau$  days before the beginning of the middle phase. The time spent getting ready for introduction into the cell nucleus DNE is amplified [12].  $\alpha_1 y$  rate of cancer enters mitosis phase to the stationary phase shown.  $\delta_1 y$  and  $k_2 I_y$  the same equation ago and  $k_4 u y$  the death rate of cancer cells by chemical drugs shows  $z$  population changes in cancer cells in stationery phase ( $G_0$ ) is described. In this equation,  $z \alpha_2 y$  the rate of cancer cells enters mitosis phase to the stationary phase shown.

Factor 2, represents a doubling of the number of cells in mitosis process.  $\alpha_3z$ ,  $\delta_3z$ ,  $k_3I_z$  are similar to previous models.  $I$  describes the population dynamics of immune cells. Immune cells are a constant source of growth rate constant ( $k$ ). Immune cells stimulate the growth of cancer cells with an expression "Michael is menten", " $\frac{eI(x+y+z)^h}{\alpha+(x+y+z)^h}$ " shown.  $\delta_4I$  immune cells show normal death rate. It is assumed that some

immune cells, cancer cells become inactive in the face of this event in the  $(c_1x + c_2y + c_3z)I$  is modeled.  $k_6uI$  is immune to death by chemical drugs. The rate of drug concentration in the body is modeled  $\dot{u}$  equation. It was supposed to end the drug in the body decreases. And half – life of the drug and concentration effects in the body as  $\dot{u} = -yu$ , indicates the dose received.

<b>Table.1.</b> Definitions of constants in the equation and the values obtained for each system state			
System constants	Definition	Parameter (for e given patient)	Obtaining source
$\alpha_1$	rate through which cell flows into the mitosis phase	1/ day	[12], [16], [17]
$\alpha_2$	rate through which cell flow into the resting phase	0.6/ day	[16], [17]
$\alpha_3$	rate through which cells leave from the resting phase to enter the cycle to reproduce	0.9/ day	[16], [17]
$c_1$	losses due to the encounters with immune cells	$0.2 \times 10^{-6}$ / cell day	[12], [17]
$c_2$		$0.8 \times 10^{-6}$ / cell day	[12], [17]
$c_3$		$0.108 \times 10^{-6}$ / cell day	[12], [17]
$\delta_1$	proportions of natural death of x, y, and I	0.11/ day	[12], [17]
$\delta_2$		0.28/ day	[12], [17]
$\delta_4$		0.3/ day	[12], [17]
$\delta_3$	rate through which cells leave from the resting state to enter the blood	$10^{-5}$ / day	[16], [17]
$p$	proportions of the growth of lymphocytes due to stimulus by cancer cells	0.2/ day	[12], [17]
$a$	speed at which the lymphocytes reach saturation level without stimulation	$0.5 \times (10^5 \text{ cell})^1$	[12], [17]
$k$	Growth rate of the lymphocytes in the absence of cancer cells	$0.15 \times 10^6$ cell /day	[12], [17]
$k_1$	rate a which lymphocytes destroy cells in different phase	$10^{-8}$ / cell day	[12], [17]
$k_2$		$0.4 \times 10^{-8}$ / cell day	[12], [17]
$k_3$		$0.1 \times 10^{-8}$ / cell day	[12], [17]
$k_4$	Proportion of drugs which eliminates cancer cells and lymphocytes	0.25/ mg- day	[12], [17]
$k_6$		0.03/ mg- day	[12], [17]
$\tau$	Resident time of cells in the inter phases (Daley)	0.5/ day	[12],[16], [17]
$\eta$	Rate of drug toxicity decay	0.5/ day	[6]
$\gamma$	Proportion of decay of the drugs	0.03/ day	[12]

The relationship between toxicity and concentration in the body is modeled by the equation  $\dot{S} = u - ns$ . Rate of change of the rate of drug toxicity and drug concentration in the body are directly likened. In Table 1 system parameters and their values for a hypothetical patient have been described.

### 3- Balance of System

In a dynamic system as a whole  $\dot{X} = F(x)$ , the non – linear Function F, the balance of the system is not unique, and sometimes it is difficult to identify all of them. As always, during the balance of system analysis are considered, to study these points and the point that is closer to conditions selected. Of the balance of the system,  $(0, 0, 0, \frac{1}{\delta_4})$  point indicating the zero point to the number of cancer cells and an acceptable is level of cell safety (the ultimate goal of cancer treatment). The point at the zero level for the concentration and toxic of the drug, as a healthy balance for your analysis and evaluation of the rest of the balance (the balance of death) are ignored. After determining the balance of the system, the first step is analysis of stability. To [18] a complete analysis of the stability of the balance of health, the results will be presented in a few cases. The delay has a significant effect on the stability of the system that can be unstable system sustainable mode or vice versa.

### 4- Stable Equilibrium Health

To design the optimal chemotherapy protocol based on lyapunor direct method, the function as the candidate Lyapunov was

assumed after using Fuzzy differential equation, control law in a way that the candidate is supposed to be a lyapunor function. Lyapunov function, if the sphere of radius  $B_R, r(x)$  is a given triangle and has Global stability, suppose a scalar function "r" the first order derivative system state variables are continuous, so:

In that case  $v(x) \rightarrow \infty$  that the equilibrium point at the origin is a stable equilibrium point totally asymptotically [21]. Case: Balance point health,  $E_0 = (0, 0, 0, \frac{k}{\delta_4}, 0, 0)$ , Asymptotic global stability is if:

Continuous partial derivatives on a direct path curve, the curve is determined by half  $(v(x) \leq 0)$ , in this case, the  $v(x)$  a Lyapunov function will be for the system. This Function has been extended to system (as a whole  $\dot{X}(t) = f(x_d, u)$ ) with time delay Lyapunov function –among Razamykhyan and Lyapunov – krashrf sky[19], [20]. Global stability, suppose a scalar function "r" the first order derivative system state variables are continuous, so:

In that case  $v(x) \rightarrow \infty$  that the equilibrium point at the origin is a stable equilibrium point total asymptotically [22]. Case: Balance point health,  $E_0 = (0, 0, 0, \frac{k}{\delta_4}, 0, 0)$ , Asymptotic global stability

As if:

$$u > \frac{\alpha_2 y}{k_4 y + \beta k_4 I \left(1 - \frac{k}{\delta_4}\right)} \quad (6-a)$$

$$\beta = \min \left\{ \frac{k_i}{c_i \frac{k}{\delta_4} + \frac{\sigma}{\alpha} I_m} \right\} \quad (6-b)$$

Proof: Lyapunor candidate function is defined as follows:

$$v = a [x + y + z + \alpha_1 \int_{\tau}^0 x(t) + \xi] d\xi + \frac{d}{z} \left( I - \frac{k}{\delta_4} \right) + eu + fs \quad (7)$$

On the curve of the path system, a derivative  $v(x)$  will be as follows:

$$v(\omega) = a \left[ \overset{\circ}{x} + \overset{\circ}{y} + \overset{\circ}{z} + \alpha_1 \{x(t) - x(t - \tau)\} \right] + d \left( I - \frac{k}{\delta_4} \right) \overset{\circ}{I} + \overset{\circ}{eu} + f_s \quad (8)$$

So we came to the conclusion:

$$v(\omega) = a [\alpha_3 z + \alpha_1 x - \delta_1 x - k_1 I_x + \alpha_1 x (x - \tau) - \alpha_2 y - \delta_2 y - k_2 I_y - k_4 u y + 2\alpha_2 y - \alpha_3 z - \delta_3 z - k_3 I + \alpha_1 \{x(t) - x(x - \tau)\}] + d \left( I - \frac{k}{\delta_4} \right) k + PI \frac{(x + y + z)}{a + (x + y + z)} - \delta_4 I - (c_1 x + c_2 y + c_3 z) I - k_6 u I + e(-yu) + f(u - ns) \quad (9)$$

After simplification, we have:

$$\begin{aligned} \dot{v} &= -a(\delta_1 x + \delta_2 y + \delta_3 z) \\ &- d\delta_4 \left( I - \frac{k}{\delta_4} \right)^2 \\ &- d(c_1 x + c_2 y + c_3 z) I^2 \\ &+ \left( -a\alpha k_1 + dc_1 \alpha \frac{k}{\delta_4} + dpI_m \right) \frac{I_x}{\alpha + (x + y + z)} \\ &+ \left( -ak_1 + dc_1 \alpha \frac{k}{\delta_4} + dpI_m \right) \frac{I_x(x + y + z)}{\alpha + (x + y + z)} \\ &+ \left( -a\alpha k_2 + dc_2 \alpha \frac{k}{\delta_4} + dpI_m \right) \frac{I_y}{\alpha + (x + y + z)} \\ &+ \left( -ak_2 + dc_2 \frac{k}{\delta_4} \right) \frac{I_y(x + y + z)}{\alpha + (x + y + z)} \\ &+ \left( -a\alpha k_3 + dc_3 \alpha \frac{k}{\delta_4} + dpI_m \right) \frac{I_z}{\alpha + (x + y + z)} \\ &+ \left( -ak_3 + dc_3 \frac{k}{\delta_4} \right) \frac{I_z}{\alpha + (x + y + z)} \\ &+ \left( -ak_3 + dc_3 \frac{k}{\delta_4} \right) \frac{I_z(x + y + z)}{\alpha + (x + y + z)} \\ &- d \frac{k}{\delta_4} p \frac{I}{\alpha + (x + y + z)} - ak_4 u I^2 \\ &+ dc_6 \frac{k}{\delta_4} u I + u(r - ey) - fns \\ &- ak_4 u y + a\alpha_3 y - dk_6 u I^2 \\ &\quad + dk_6 \frac{k}{\delta_4} u I < 0 \Rightarrow a \\ &\quad < \frac{k_6 u I^2 - k_6 \frac{k}{\delta_4} u I}{\alpha_3 y - k_4 u y} d \end{aligned} \quad (10)$$

However  $\dot{v}$  because is negative, it must be negative sentences. Considering the fact that the number of cells and the concentration of

drug toxicity values should be no negative values:

$$d < \left[ \left( \frac{k_i}{k_i \frac{k}{\delta_4} + \frac{e}{a} \text{Im}} \right) \right] a \quad (11)$$

$i = 1, 2, 3, \dots$

$$-ak_4uy + a\alpha_3y - dk_6ul^2 + dk_6 \frac{k}{\delta_4} ul < 0 \Rightarrow a$$

$$\frac{k_6ul^2 - k_6 \frac{k}{\delta_4} ul}{\alpha_3y - k_4uy} < d \quad (12)$$

And finally:

$$f < er \quad (13)$$

The bare conditions:  $v(x)$  a Lyapunor function for the system. If the values  $e, f$  compared with  $a, b$  they would be too small. If we assume that the smallest amount of  $e, f$  as compared  $a, b$ , by placing one of the two relationships (11), (12), the other control law is obtained:

$$u > \frac{\alpha_2y}{k_4y + \beta k_6 \left(1 - \frac{k}{\delta_4}\right)} \quad (14)$$

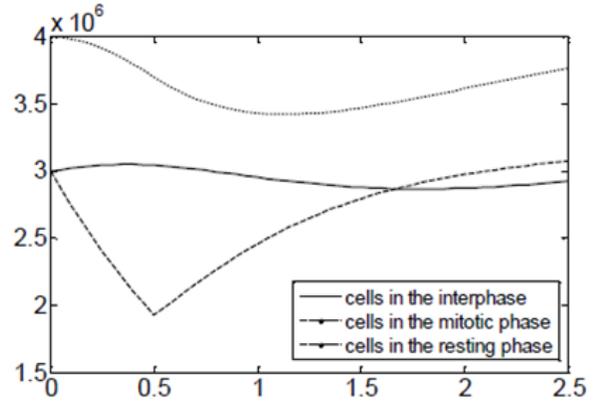
$$\beta = \min \left\{ \frac{k_i}{c_i \frac{k}{\delta_4} + \frac{e}{\alpha} \text{Im}} \right\} \quad (15)$$

### 5- Of the drug based on Fuzzy equations, and Lyapunor stability criteria

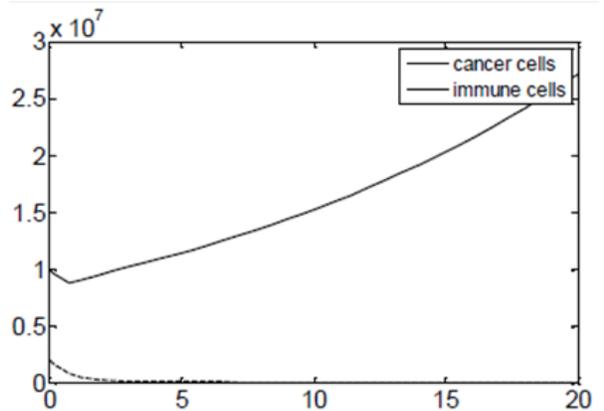
Parameters were given to the patient so that the equilibrium point is unstable health. The continuous partial derivatives on a direct parameter in table (1) have been given. The initial condition of the system behavior is obtained in the absence of chemotherapy.

$$x(t) = 3 \times 10^{+6}, y(t) = 3 \times 10^{+6}, z(t) = 4 \times 10^{+6}, I(t) = 2 \times 10^{+6}$$

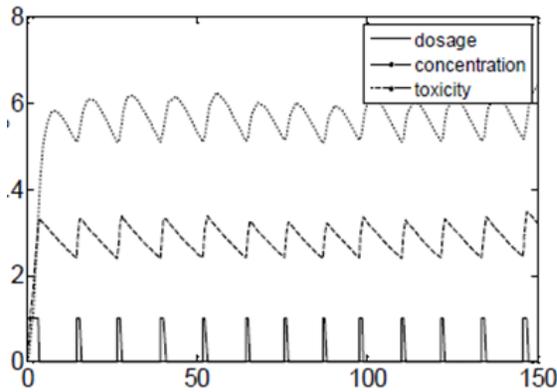
Due to the unstable equilibrium of health systems around, it points to the death of Gil as one of balance. (Figures 1, 2) In figure 3 the way of the drug based obtained with the concentration and toxicity criteria Lyapunor and in the figure (4) changes in the population of cancer cells and immune cells of the protocol can be obtained. Forms (3), (4) 7 sessions of chemotherapy after about 50 days, the number of cancer cells has declined.



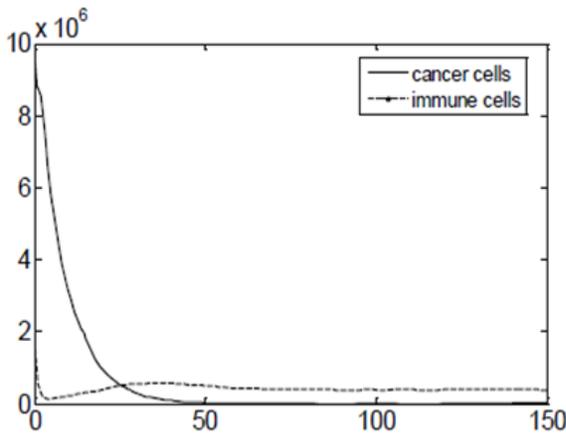
**Fig.1.** Change in the absence of cancer cells in different phases of the drug



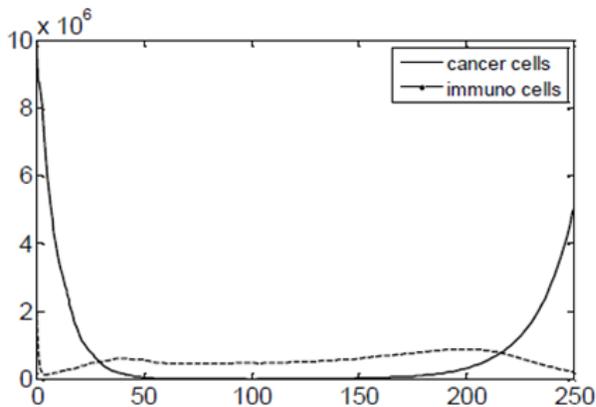
**Fig.2.** Change in the total population of cancer cells and immune cells in the absence of drug



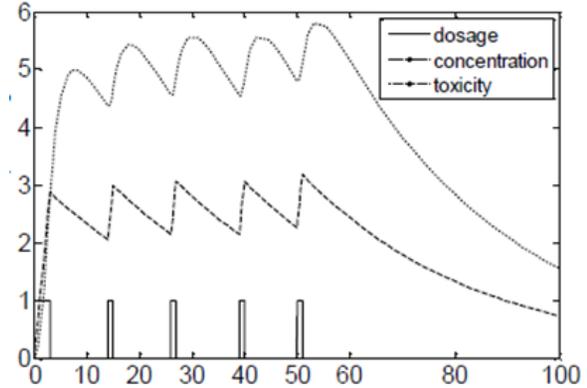
**Fig.3.** model drug dosage Lyapunov criteria in accordance with the concentration and toxicity



**Fig.4.**Change in the total population of cancer cells and immune cells consistent pattern of figure 3



**Fig.5.**Model drug dosage Lyapunov criteria in accordance with the new conditions and change in concentration and toxicity drug dosage



**Fig.6.** Change in the total population of cancer cells and immune cells in the model drug dosage Figure5

It can be seen that to keep the system in good condition of the drug, it should continue to be on going. But to do so due to an increase in side effects and toxicity in the body is virtually impossible, therefore since the physicians of chemotherapy until the cancer cells continue to be higher, the amount specified, in order to improve the condition of other drug obtained from case of exponent was added so that after reaching zero the number of cancer cells stops (fig. 5). The main problem in this case is that after the use of the drug control law, the possibility of the growth of cancer cells and to reaches a significant number there (fig. 6). To solve this problem, two solutions are recommended: First, it can be passed after a certain number of cancer cells than chemotherapy again resumed. This continued weakness of the patients and increased the toxicity of the drug in the body. The second solution is using

therapeutic vaccine after the period of chemotherapy. Vaccine therapy can change the parameters of the health system and strengthening the balance point.

## 6- Conclusion

In this study, a new mathematical model to describe the growth of cancer cells and immune cells as well as proposed changes in the concentration and toxicity of the drug and applying Lyapunov stability theorem, the optimal treatment protocol, was designed. To prevent re-growth of the system, parameters and the optimal balance point should be sustainable. Immune cells as well as proposed changes in the concentration and toxicity of the drug and applying Lyapunov stability theorem, the optimal treatment protocol was designed. To prevent re-growth of the system parameters and the optimal balance point should be sustainable.

## References

- [1] Eisen, M.M.(1979). *Mathematical Models in Cell Biology and Cancer Chemotherapy*. Volume 30 of *Lecture Notes in Biomathematics*, Springer-Verlag, New York.
- [2] Knolle, H. (1988). *Cell Kinetic Modeling and the Chemotherapy of Cancer*", Volume 75 of *Lecture Notes in Biomathematics*, Springer-Verlag, New York.
- [3] Swierniak A., Kimmel M., Smieja J. (2009). *Mathematical modeling as a tool for planning anticancer therapy*. *European Journal of Pharmacology* 625, 108–121.
- [4] Kimmel, M. and Swierniak, A.(2006).Using control theory to make cancer chemotherapy beneficial from phase dependence and resistant to drug resistance", *J. Math. Biosci.*
- [5] Ghaffari A., Karimi M. (2009).Optimal Design of Chemotherapy Drug Protocol for Cancer Treatment Based on a New Mathematical Model" *Int. J. Modeling, Identification and Control*.
- [6] Ghaffari A., Nasserifar N. (2009). *Mathematical Modeling and Lyapunov based Drug Administration in Cancer Chemotherapy*. *Iranian Journal of Electrical and Electrical Engineering*.
- [7] Webb, G.F.(1992). A cell population model of periodic chemotherapy Treatment. In *Biomedical Modeling and Simulation*, Elsevier Science, .92-83
- [8] Kheifetz, Y., Kogan, Y., Agur, Z.,"Long-range predictability in models of cell populations subjected to phase-specific drugs: Growth rate approximation using properties of positive compact operators," *Mathematical Models & Methods in the Applied Sciences*. In Press.
- [9] Birkhead, B.G., Rakin, E.M., Gallivan, S., Dones, L. and Rubens R.D. (1987). A mathematical model of the development of drug resistance to cancer chemotherapy", *J. Cancer.Clin.Oncol.*23(9), 1421-1427.
- [10] Swan, G.W. (1987). *Tumor growth models and cancer chemotherapy*", In *Cancer Modeling*, Volume 83, Chapter 3, (Edited by J.R. Thompson and B. Brown), Marcel Dekker, New York, 91-179.
- [11] Kirschner, D., Panetta, J. (1998). *Modeling immunotherapy of the tumor immune interaction*. *J. Math. Biol.* 37, 235-252.
- [12] Villasana, M. (2001). *A delay differential equation model for tumor Growth*. PhD thesis, Mathematical Department, Claremont University,CA, USA.
- [13] Kozusko, F. et al. (2001). A mathematical model of invitro cancer cell growth and treatment with the antimitotic agent curacin A," *Math.Biosci.*170, 1-16.
- [14] T. Burden, J. Ernstberger and K. Renee Fister (2004). *Optimal control applied to immunotherapy*", *Discrete and continuous dynamical systems-series B* Vol 4.
- [15] K.R. Fister and J.H. Donnelly (2005). *Immunotherapy: an optimal control theory approach*. *Mathematical Bioscience and engineering* Vol 2.

- [16] Liu, W., Hillen, T., Freedman, H., I. (2007). A Mathematical Model for M-PHASE Specific Chemotherapy Including the G0-PHASE and Immune response, J. of MATHEMATICAL BIOSCIENCES AND ENGINEERING Volume 4, Number 2.
- [17] Mackey, M.C. (2001). Cell kinetic status of hematopoietic stem cells. Cell Prolif., 34, 71-83.
- [18] Kuznetsov, A., et al. (1994). Nonlinear dynamics of immunogenic tumors: Parameter estimation and global bifurcation analysis", B. Math. Biol., 321-295, 56
- [19] Jankovic, M. (1999). Control Lyapunov-Razumikhin functions for time delay systems. Proceedings of CDC, Phoenix, AZ.
- [20] Jankovic, M. (2000). Extension of control Lyapunov functions to time delay systems. Proceedings of the 39' IEEE Conference on Decision and Control, Sydney, Australia.
- [21] Slotine, J.J.E., Li, W.(1991). Applied Nonlinear Control, Prentice Hall International, Englewood Cliffs pp. 58-65.
- [22] Nikdel, Parisa, et al. "Improved Takagi–Sugeno fuzzy model-based control of flexible joint robot via Hybrid-Taguchi genetic algorithm." Engineering Applications of Artificial Intelligence 33 (2014): 12-20.
- [23] Pourmahmood, Mohammad, Mohammd Esmaeel Akbari, and Amin Mohammadpour. "An efficient modified shuffled frog leaping optimization algorithm." Int. J. Comput. Appl 32.1 (2011): 0975-8887.